An Integrated Disaster Relief Supply Chain Network Model With Time Targets and Demand Uncertainty





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Outlook

- Background and Introduction
- Integrated Network Model for Disaster Relief Supply Chains
- Numerical Example and Results
- Summary and Conclusion

The number of natural disasters and the sizes of the populations affected by such events have been growing (Schultz, Koenig, and Noji (1996) and Nagurney and Qiang (2009)).

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Scientists are warning that we can expect more frequent extreme weather events in the future.

For instance, tropical cyclones which include hurricanes in the US are expected to be stronger as a result of global warming (Sheppard (2011) and Borenstein (2012)).



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An Integrated Disaster Relief Supply Chain Network Model

The amount of damage and loss following a disaster depends on the vulnerability of the affected region, and on its ability to respond (and recover) in a timely manner, also referred to as resilience.

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Hence, being prepared against potential disasters leads to reduced vulnerability and a lower number of fatalities.

"During a natural disaster, one has only two options: **to become a victim, or to become a responder**" (Alvendia-Quero (2012)).

Background: Disaster Relief Supply Chains

The *complexity* of disaster relief supply chains originates from *several inherent factors*:

- Large demands for relief products,
- Level of uncertainty,
- **Irregularities** in the size, the timing, and the location of relief product demand patterns,
- Disaster-driven supply chains are typically incident-responsive, and
- Develop new networks of relationships within days or even hours, and have very short life-cycles.





Background: Criticality of Time

TIME plays a substantial role in the construction and operation of disaster relief networks.

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FEMA's key benchmarks in response and recovery:

- To meet the survivors initial demands within 72 hours,
- To restore basic community functionality within 60 days, and
- To return to as normal of a situation within 5 years.

Relevant Literature

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Mathematical Model

We propose an integrated supply chain network model for disaster relief.

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Our mathematical framework is of system-optimization type where the organization aims to satisfy the uncertain demands subject to the minimization of total operational costs while the sequences of activities leading to the ultimate delivery of the relief good are targeted to be completed within a certain time.

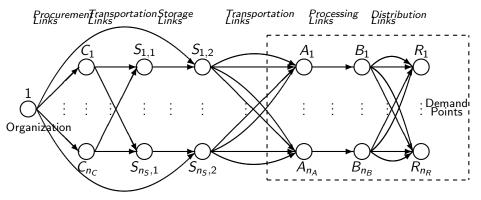


Figure 1: Network Topology of the Integrated Disaster Relief Supply Chain

G = [N, L]: supply chain network graph, N: set of nodes, L: set of links (arcs).

Mathematical Model

Notations:

 \mathcal{P}_k : set of paths connecting the origin (node 1) to demand point k, \mathcal{P} : set of all paths joining the origin node to the destination nodes, and n_p : total number of paths in the supply chain.

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Total Operational Cost Function

$$\hat{c}_a(f_a) = f_a \times c_a(f_a), \qquad \forall a \in L,$$

(1)

where:

 f_a : flow of the disaster relief product on link *a*, and $c_a(f_a)$: unit operational cost function on link *a*.

Probability Distribution of Demand

$$P_k(D_k) = P_k(d_k \leq D_k) = \int_0^{D_k} \mathcal{F}_k(t) dt, \qquad k = 1, \dots, n_R, \quad (2)$$

where:

- d_k : actual value of demand at point k,
- P_k : probability distribution function of demand at point k,
- \mathcal{F}_k : probability density function of demand at point k.

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Demand Shortage and Surplus

$$\Delta_k^- \equiv \max\{0, d_k - v_k\}, \qquad k = 1, \dots, n_R, \tag{3a}$$

$$\Delta_k^+ \equiv \max\{0, v_k - d_k\}, \qquad k = 1, \dots, n_R, \tag{3b}$$

where:

 v_k : "projected demand" for the disaster relief item at point k.

Expected Values of Shortage and Surplus

$$E(\Delta_k^-) = \int_{v_k}^{\infty} (t - v_k) \mathcal{F}_k(t) dt, \qquad k = 1, \dots, n_R, \qquad (4a)$$

$$E(\Delta_k^+) = \int_0^{v_k} (v_k - t) \mathcal{F}_k(t) dt, \qquad k = 1, \dots, n_R.$$
 (4b)

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$$E(\Delta_k^+) = \int_0^{v_k} (v_k - t) \mathcal{F}_k(t) dt, \qquad k = 1, \dots, n_R.$$
 (4b)

Expected Penalty due to Shortage and Surplus

$$E(\lambda_k^- \Delta_k^- + \lambda_k^+ \Delta_k^+) = \lambda_k^- E(\Delta_k^-) + \lambda_k^+ E(\Delta_k^+), \qquad k = 1, \dots, n_R, \quad (5)$$

where:

 λ_k^- : unit penalty associated with the shortage of the relief item at point k,

 λ_k^+ : unit penalty associated with the surplus of the relief item at point k.

Path Flows

$$x_p \geq 0, \qquad \forall p \in \mathcal{P}.$$

(6)

 x_p : flow of the disaster relief goods on path p joining node 1 with a demand node.

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Relationship between Path Flows and Projected Demand

$$v_k \equiv \sum_{p \in \mathcal{P}_k} x_p, \qquad k = 1, \dots, n_R.$$
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 (7)

Relationship between Link Flows and Path Flows

$$f_{a} = \sum_{p \in \mathcal{P}} x_{p} \ \delta_{ap}, \qquad orall a \in L.$$

(8)

 δ_{ap} is equal to 1 if link a is contained in path p and is 0, otherwise.

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Capturing Time Aspect in Formulation

Completion Time

$$\tau_a(f_a) = g_a f_a + h_a, \qquad \forall a \in L, \tag{9}$$

where:

 τ_a : completion time of the activity on link *a*. Note: $h_a \ge 0$, and $g_a \ge 0$.

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Completion Time on Paths

$$\tau_{p} = \sum_{a \in L} \tau_{a}(f_{a})\delta_{ap} = \sum_{a \in L} (g_{a}f_{a} + h_{a})\delta_{ap}, \qquad \forall p \in \mathcal{P}.$$
(10)

Where:

 τ_p : completion time of the sequence of activities on path p.

$$h_p = \sum_{a \in L} h_a \delta_{ap}, \qquad \forall p \in \mathcal{P}.$$
(11)

Hence,

$$\tau_{p} = h_{p} + \sum_{a \in L} g_{a} f_{a} \delta_{ap}, \qquad \forall p \in \mathcal{P}.$$
(12)

 h_p : sum of the uncongested terms h_a s on path p.

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Time Targets

$$au_p \leq T_k, \quad \forall p \in \mathcal{P}_k; \quad k = 1, \dots, n_R,$$

(13)

 T_k : target for the completion time of the activities on paths corresponding to demand point k determined by the organization's decision-maker.

$$\sum_{a\in L} g_a f_a \delta_{ap} \leq T_k - h_p, \qquad \forall p \in \mathcal{P}_k; \quad k = 1, \dots, n_R.$$
(14)

$$T_{kp} = T_k - h_p, \qquad \forall p \in \mathcal{P}_k; \quad k = 1, \dots, n_R.$$
(15)

 T_{kp} : target time for demand point k with respect to path p.

$$\sum_{a\in L} g_a f_a \delta_{ap} \leq T_{kp}, \qquad \forall p \in \mathcal{P}_k; \quad k = 1, \dots, n_R.$$
 (16)

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$$\sum_{a \in L} g_a f_a \delta_{ap} \leq T_{kp}, \qquad \forall p \in \mathcal{P}_k; \quad k = 1, \dots, n_R.$$
(16)

Late Delivery (Deviations) with Respect to Target Times

$$\sum_{a \in L} g_a f_a \delta_{ap} - z_p \leq T_{kp}, \qquad \forall p \in \mathcal{P}_k; \quad k = 1, \dots, n_R.$$
(17)

 z_p : amount of deviation with respect to target time T_{kp} corresponding to the "late" delivery of product to point k on path p.

Non-negativity

$$z_p \ge 0, \qquad \forall p \in \mathcal{P}_k; \quad k = 1, \dots, n_R.$$
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Time Constraint

$$\sum_{q\in\mathcal{P}}\sum_{a\in L}g_{a}x_{q}\delta_{aq}\delta_{ap}-z_{p}\leq T_{kp}, \qquad \forall p\in\mathcal{P}_{k}; \quad k=1,\ldots,n_{R}.$$
(19)

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(19)

$$\hat{C}_{p}(x) = x_{p} \times C_{p}(x) = x_{p} \times \sum_{a \in L} c_{a}(f_{a})\delta_{ap}, \qquad \forall p \in \mathcal{P},$$
(20)

 $\hat{C}_p(x)$: total operational cost function on path p. C_p : unit operational cost on path p.

$\gamma_k(z)$: tardiness penalty function corresponding to demand point k.

Optimization Formulation

SI

Minimize
$$\sum_{p \in \mathcal{P}} \hat{C}_p(x) + \sum_{k=1}^{n_R} (\lambda_k^- E(\Delta_k^-) + \lambda_k^+ E(\Delta_k^+)) + \sum_{k=1}^{n_R} \gamma_k(z)$$
, (21)
ubject to: constraints (6), (18), and (19).

$\gamma_k(z)$: tardiness penalty function corresponding to demand point k.

Optimization Formulation

Minimize
$$\sum_{p \in \mathcal{P}} \hat{C}_p(x) + \sum_{k=1}^{n_R} (\lambda_k^- E(\Delta_k^-) + \lambda_k^+ E(\Delta_k^+)) + \sum_{k=1}^{n_R} \gamma_k(z)$$
, (21)

subject to: constraints (6), (18), and (19).

Feasible Set

$$K = \{ (x, z, \omega) | x \in R_{+}^{n_{p}}, z \in R_{+}^{n_{p}}, \text{ and } \omega \in R_{+}^{n_{p}} \},$$
(23)

where x is the vector of path flows, z is the vector of time deviations on paths, and ω is the vector of Lagrange multipliers corresponding to (19).

Variational Inequality Formulation

The optimization problem (21), subject to its constraints (6), (18), and (19), is equivalent to the variational inequality problem: determine the vector of optimal path flows, the vector of optimal path time deviations, and the vector of optimal Lagrange multipliers $(x^*, z^*, \omega^*) \in K$, such that:

$$\sum_{k=1}^{n_R} \sum_{p \in \mathcal{P}_k} \left[\frac{\partial \hat{\mathcal{C}}_p(x^*)}{\partial x_p} + \lambda_k^+ \mathcal{P}_k \left(\sum_{q \in \mathcal{P}_k} x_q^* \right) - \lambda_k^- (1 - \mathcal{P}_k \left(\sum_{q \in \mathcal{P}_k} x_q^* \right)) \right] \\ + \sum_{q \in \mathcal{P}} \sum_{a \in L} \omega_q^* g_a \delta_{aq} \delta_{ap} \times [x_p - x_p^*] + \sum_{k=1}^{n_R} \sum_{p \in \mathcal{P}_k} \left[\frac{\partial \gamma_k(z^*)}{\partial z_p} - \omega_p^* \right] \times [z_p - z_p^*] \\ + \sum_{k=1}^{n_R} \sum_{p \in \mathcal{P}_k} \left[T_{kp} + z_p^* - \sum_{q \in \mathcal{P}} \sum_{a \in L} g_a x_q^* \delta_{aq} \delta_{ap} \right] \times [\omega_p - \omega_p^*] \ge 0, \qquad \forall (x, z, \omega) \in \mathcal{K},$$

$$(24)$$

where

$$\frac{\partial \hat{\mathcal{C}}_{p}(x)}{\partial x_{p}} \equiv \sum_{a \in L} \frac{\partial \hat{\mathcal{C}}_{a}(f_{a})}{\partial f_{a}} \delta_{ap}, \quad \forall p \in \mathcal{P}_{k}; \ k = 1, \dots, n_{R}.$$
(25)

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Solution Method and Numerical Examples







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Solution Algorithm

Explicit Formulae for the Ender Marked Applied to the Variational Inequality (24)

At iteration $\tau + 1$:

$$x_p^{\tau+1} = \max\{0, x_p^{\tau} + a_{\tau}(\lambda_k^-(1 - P_k(\sum_{q \in \mathcal{P}_k} x_q^{\tau})) - \lambda_k^+ P_k(\sum_{q \in \mathcal{P}_k} x_q^{\tau}) - \frac{\partial \hat{C}_p(x^{\tau})}{\partial x_p}$$

$$-\sum_{q\in\mathcal{P}}\sum_{a\in L}\omega_{q}^{\tau}g_{a}\delta_{aq}\delta_{ap})\},\qquad \forall p\in\mathcal{P}_{k};\quad k=1,\ldots,n_{R},\qquad(31)$$

$$z_{p}^{\tau+1} = \max\{0, z_{p}^{\tau} + a_{\tau}(\omega_{p}^{\tau} - \frac{\partial\gamma_{k}(z^{\tau})}{\partial z_{p}})\}, \quad \forall p \in \mathcal{P}_{k}; \quad k = 1, \dots, n_{R}, \text{ and}$$

$$(32)$$

$$\omega_{p}^{\tau+1} = \max\{0, \omega_{p}^{\tau} + a_{\tau}(\sum_{q \in \mathcal{P}} \sum_{a \in L} g_{a} x_{q}^{\tau} \delta_{aq} \delta_{ap} - T_{kp} - z_{p}^{\tau}\},$$

$$\forall p \in \mathcal{P}_k; \qquad k = 1, \dots, n_R. \tag{33}$$

A Large Scale Numerical Example

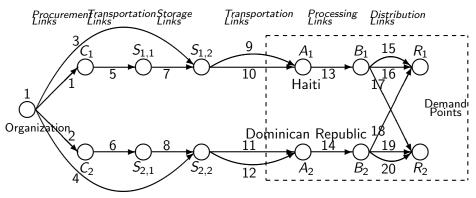


Figure 2: Network Topology of the Larger Disaster Relief Supply Chain Numerical Example

Unit shortage and surplus penalties at demand points R_1 and R_2 :

$$egin{aligned} \lambda^-_{R_1} &= 10,000, \ \lambda^+_{R_1} &= 100, \ \lambda^-_{R_2} &= 7,500, \ \lambda^+_{R_2} &= 150. \end{aligned}$$

Target times of delivery at demand points:

$$T_{R_1} = 72, \ T_{R_2} = 70.$$

Tardiness penalty functions at demand points:

$$\gamma_{R_1}(z) = 3(\sum_{p \in \mathcal{P}_{R_1}} z_p^2), \quad \gamma_{R_2}(z) = 3(\sum_{p \in \mathcal{P}_{R_2}} z_p^2).$$

Unit shortage and surplus penalties at demand points R_1 and R_2 :

$$egin{aligned} \lambda^-_{R_1} &= 10,000, \; \lambda^+_{R_1} &= 100, \ \lambda^-_{R_2} &= 7,500, \; \lambda^+_{R_2} &= 150. \end{aligned}$$

Target times of delivery at demand points:

$$T_{R_1} = 72, \ T_{R_2} = 70.$$

Tardiness penalty functions at demand points:

$$\gamma_{R_1}(z) = 3(\sum_{p \in \mathcal{P}_{R_1}} z_p^2), \quad \gamma_{R_2}(z) = 3(\sum_{p \in \mathcal{P}_{R_2}} z_p^2).$$

The Euler method (cf.(31)–(33)) for the solution of variational inequality (24) was implemented in FORTRAN on a PC at the University of Massachusetts Amherst. We set the sequence as $\{a^{\tau}\} = .1(1, \frac{1}{2}, \frac{1}{2}, ...)$, and the convergence tolerance was 10^{-6} .

Table 2: Functions and the Optimal Flows on Links in the Numerical Example

Link	$\hat{c}_a(f_a)$	$\tau_a(f_a)$	f_a^*
1	$3f_1^2 + 2f_1$	0	19.22
2	$2f_2^2 + 2.5f_2$	0	20.02
3	$5f_3^2 + 4f_3$	$3f_3 + 3$	0.00
4	$4.5f_4^2 + 3f_4$	$4f_4 + 2$	0.00
5	$f_5^2 + 2f_5$	0	19.22
6	$f_6^2 + .5f_6$	0	20.02
7	$2.5f_7^2 + 3f_7$	0	19.22
8	$3.5f_8^2 + 2f_8$	0	20.02
9	$7f_9^2 + 5f_9$	$2f_9 + 2$	19.22
10	$4f_{10}^2 + 6f_{10}$	$10f_{10} + 6$	0.00
11	$2.5f_{11}^2 + 4f_{11}$	$7.5f_{11} + 5$	0.23
12	$4.5f_{12}^2 + 5f_{12}$	$1.5f_{12} + 1.5$	19.79
13	$2f_{13}^2 + 4f_{13}$	$2f_{13} + 2$	19.22
14	$f_{14}^2 + 3f_{14}$	$1.5f_{14} + 1$	20.02
15	$4f_{15}^2 + 5f_{15}$	$3f_{15} + 3$	13.95
16	$2.5f_{16}^2 + 2f_{16}$	$5f_{16} + 4$	5.28
17	$3f_{17}^2 + 4f_{17}$	$6.5f_{17} + 3$	0.00
18	$4f_{18}^2 + 4f_{18}$	$7f_{18} + 5$	6.85
19	$3f_{19}^2 + 3f_{19}$	$4f_{19} + 5$	5.68
20	$3.5f_{20}^2 + 5f_{20}$	$3.5f_{20} + 4$	7.49

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Background Model Numerical Example Summary

Table 3: Path Definitions, Target Times, Optimal Path Flows, Time Deviations, and Lagrange Multipliers for the Numerical Example

	Path Definition	T	*	*	*
		T_{kp}	x_p^*	z_p^*	ω_p^*
	$p_1 = (1, 5, 7, 9, 13, 15)$	65	13.95	53.66	321.99
	$p_2 = (1, 5, 7, 9, 13, 16)$	64	5.28	39.23	235.39
	$p_3 = (1, 5, 7, 10, 13, 15)$	61	0.00	19.32	115.90
	$p_4 = (1, 5, 7, 10, 13, 16)$	60	0.00	4.83	28.99
\mathcal{P}_{R_1} : Set of Paths	$p_5 = (2, 6, 8, 11, 14, 18)$	61	0.06	18.67	112.03
Corresponding to	$p_6 = (2, 6, 8, 12, 14, 18)$	64.5	6.79	43.12	258.75
Demand Point R_1	$p_7 = (3, 9, 13, 15)$	62	0.00	56.66	339.99
	$p_8 = (3, 9, 13, 16)$	61	0.00	42.23	253.39
	$p_9 = (3, 10, 13, 15)$	58	0.00	22.34	134.05
	$p_{10} = (3, 10, 13, 16)$	57	0.00	7.84	47.03
	$p_{11} = (4, 11, 14, 18)$	59	0.00	20.71	124.24
	$p_{12} = (4, 12, 14, 18)$	62.5	0.00	45.24	271.46
	$p_{13} = (1, 5, 7, 9, 13, 17)$	63	0.00	13.87	83.25
	$p_{14} = (1, 5, 7, 10, 13, 17)$	59	0.00	0.00	0.00
	$p_{15} = (2, 6, 8, 11, 14, 19)$	59	0.13	0.00	0.00
	$p_{16} = (2, 6, 8, 11, 14, 20)$	60	0.04	0.00	0.00
\mathcal{P}_{R_2} : Set of Paths	$p_{17} = (2, 6, 8, 12, 14, 19)$	62.5	5.55	19.91	119.44
Corresponding to	$p_{18} = (2, 6, 8, 12, 14, 20)$	63.5	7.45	22.40	134.43
Demand Point R_2	$p_{19} = (3, 9, 13, 17)$	60	0.00	16.90	101.41
	$p_{20} = (3, 10, 13, 17)$	56	0.00	0.00	0.00
	$p_{21} = (4, 11, 14, 19)$	57	0.00	0.00	0.00
	$p_{22} = (4, 11, 14, 20)$	58	0.00	0.00	0.00
	$p_{23} = (4, 12, 14, 19)$	60.5	0.00	21.96	131.77
	$p_{24} = (4, 12, 14, 20)$	61.5	0.00	24.48	146.85

Numerical Example: A Variant

We assumed that the organization will now procure the items locally and, hence, the time functions associated with the direct procurement links 3 and 4 are now greatly reduced. The remainder of the input data remains as in the previous example.

As in Table 4, now both the storage links for pre-positioning (links 7 and 8) and for post-disaster procurement (links 3 and 4) have positive flows.

Table 4: Numerical Example Variant - Optimal Link Flows

Link	$\hat{c}_a(f_a)$	$\tau_a(f_a)$	f_a^*
1	$3f_1^2 + 2f_1$	0	12.02
2	$2f_2^2 + 2.5f_2$	0	11.21
3	$5f_3^2 + 4f_3$	$.1f_3 + 1$	7.35
4	$4.5f_4^2 + 3f_4$	$.1f_4 + 1$	8.88
5	$f_5^2 + 2f_5$	0	12.02
6	$f_6^2 + .5f_6$	0	11.21
7	$2.5f_7^2 + 3f_7$	0	12.02
8	$3.5f_8^2 + 2f_8$	0	11.21
9	$7f_9^2 + 5f_9$	$2f_9 + 2$	19.37
10	$4f_{10}^2 + 6f_{10}$	$10f_{10} + 6$	0.00
11	$2.5f_{11}^2 + 4f_{11}$	$7.5f_{11} + 5$	0.24
12	$4.5f_{12}^2 + 5f_{12}$	$1.5f_{12} + 1.5$	19.86
13	$2f_{13}^2 + 4f_{13}$	$2f_{13} + 2$	19.37
14	$f_{14}^2 + 3f_{14}$	$1.5f_{14} + 1$	20.10
15	$4f_{15}^2 + 5f_{15}$	$3f_{15} + 3$	14.04
16	$2.5f_{16}^2 + 2f_{16}$	$5f_{16} + 4$	5.33
17	$3f_{17}^2 + 4f_{17}$	$6.5f_{17} + 3$	0.00
18	$4f_{18}^2 + 4f_{18}$	$7f_{18} + 5$	6.84
19	$3f_{19}^2 + 3f_{19}$	$4f_{19} + 5$	5.72
20	$3.5f_{20}^2 + 5f_{20}$	$3.5f_{20} + 4$	7.53

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- includes penalties associated with shortages/surpluses at the demand points with respect to the uncertain demand, and
- enables prioritizing the demand points based on the population, geographic location, etc., by assigning different time targets.

Thank You!



Photos

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