Lecture 7: An Integrated Disaster Relief Model

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Background: Natural Disasters

This lecture is based on the paper: “An Integrated Disaster Relief Supply Chain Network Model with Time Targets and Demand Uncertainty,” Anna Nagurney, Amir H. Masoumi, and Min Yu, *Regional Science Matters: Studies Dedicated to Walter Isard*, P. Nijkamp, A. Rose, and K. Kourtit, Editors, Springer International Publishing Switzerland (2015), pp 287-318, where references can be found.
Our recent book focuses on supply chains for perishable products with chapters also relevant to disaster relief supply chains (on blood supply chains and pharmaceuticals).
The number of natural disasters and the sizes of the populations affected by such events have been growing (Schultz, Koenig, and Noji (1996) and Nagurney and Qiang (2009)).

Scientists are warning that we can expect more frequent extreme weather events in the future. For example, tropical cyclones, which include hurricanes in the United States, are expected to be stronger as a result of global warming (Sheppard (2011) and Borenstein (2012)).
Background: Natural Disasters
The amount of damage and loss following a disaster depends on the **vulnerability** of the affected region, and on its ability to respond (and recover) in a timely manner, also referred to as **resilience**.
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Hence, being prepared against potential disasters leads to reduced vulnerability and a lower number of fatalities.

“During a natural disaster, one has only two options: to become a victim, or to become a responder” (Alvendia-Quero (2012)).
Background: Disaster Relief Supply Chains

The \textit{complexity} of disaster relief supply chains originates from several \textit{inherent factors}:

\begin{itemize}
  \item \textbf{Large demands} for relief products,
  \item Level of \textbf{uncertainty},
  \item \textbf{Irregularities} in the size, the timing, and the location of relief product demand patterns,
  \item Disaster-driven supply chains are typically \textbf{incident-responsive}, and
  \item may result in new networks of relationships within \textbf{days} or even \textbf{hours}, and have very \textbf{short life-cycles}.
\end{itemize}
**TIME** plays a substantial role in the construction and operation of disaster relief networks.
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**FEMA’s key benchmarks in response and recovery:**

- To meet the survivors initial demands within **72 hours**, 
- To restore basic community functionality within **60 days**, and 
- To return to as normal of a situation within **5 years**.
Disasters necessarily affect regions and pose challenges in all phases of disaster management. Vivid examples of disasters such as Hurricane Katrina in August 2005, the Haiti earthquake in January 2010, Fukushima in March 2011, and Superstorm Sandy in October 2012 have challenged researchers, practitioners, as well as policy-makers and other decision-makers and have yielded multidisciplinary approaches to models, methods, and techniques with major contributors being from regional science (cf. West and Lenze (1994), Israelevich et al. (1997), Rose et al. (1997), Okuyama, Hewings, and Sonis (1999), Cho et al. (2001), Okuyama (2004), Rose and Liao (2005), Ham, Kim, and Boyce (2005), Greenberg, Lahr, and Mantell (2007), Grubesic et al. (2008), Reggiani and Nijkamp (2009), Nagurney and Qiang (2009), and Rose (2009), among others).


Additional Relevant Literature Chronology


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In addition, our model allows for the **pre-disaster and the post-disaster procurement of relief items**, and involves the time and the cost associated with each strategy or a combination of both.
Our model, in contrast to much of the literature, does not consider targets for cost; instead, it minimizes the total operational costs of the activities in the supply chain network.

In addition, our model allows for the pre-disaster and the post-disaster procurement of relief items, and involves the time and the cost associated with each strategy or a combination of both.

Moreover, we handle nonlinear costs, which capture congestion effects, a big issue in disaster relief, and an aspect that has been missing from much of the literature on the topic (cf. Haghani and Oh (1996)).
Our Goal is to Assist in Disaster Relief (Pre and Post)
The disaster relief supply chain network model captures both the **preparedness phase** and the **response phase** of the disaster management cycle (with the other two phases being mitigation and recovery) (Tomasini and Van Wassenhove (2009)).

- We take into account the pre-disaster preparations including the procurement, the pre-positioning, and the storage of disaster relief items given the estimated demand in disaster-prone areas.

- We also take into consideration the relevant issues surrounding the transportation and the ultimate distribution of the relief goods to the demand points once a potential disaster takes place.

- Furthermore, the case where an organization procures the humanitarian aid items after the occurrence of a disaster is also integrated into our model.
We propose an integrated supply chain network model for disaster relief.
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Our mathematical framework is of system-optimization type where the organization aims to satisfy the uncertain demands subject to the minimization of total operational costs while the sequences of activities leading to the ultimate delivery of the relief good are targeted to be completed within a certain time.
Integrated Disaster Relief Supply Chain Network Model

Figure: Network Topology of the Integrated Disaster Relief Supply Chain

\[ G = [N, L]: \text{supply chain network graph,} \]
\[ N: \text{set of nodes,} \ L: \text{set of links (arcs).} \]
**Notation**

\( \mathcal{P}_k \): the set of paths connecting the origin (node 1) to demand point \( k \),

\( \mathcal{P} \): the set of all paths joining the origin node to the destination nodes, and

\( n_p \): the total number of paths in the supply chain.
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Total Operational Cost Functions

\[ \hat{c}_a(f_a) = f_a \times c_a(f_a), \quad \forall a \in L, \]  \hspace{1cm} (1)

where:
\( f_a \): the flow of the disaster relief product on link \( a \), and
\( c_a(f_a) \): the unit operational cost function on link \( a \).
Probability Distributions of Demand at Demand Points

\[ P_k(D_k) = P_k(d_k \leq D_k) = \int_0^{D_k} F_k(t) dt, \quad k = 1, \ldots, n_R, \quad (2) \]

\( d_k \): the actual value of demand at point \( k \),
\( P_k \): the probability distribution function of demand at point \( k \),
\( F_k \): the probability density function of demand at point \( k \).
Probability Distributions of Demand at Demand Points

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- \( P_k \): the probability distribution function of demand at point \( k \),
- \( \mathcal{F}_k \): the probability density function of demand at point \( k \).

Demand Shortages and Surpluses

\[
\Delta_k^- \equiv \max\{0, d_k - v_k\}, \quad k = 1, \ldots, n_R, \quad (3a) \\
\Delta_k^+ \equiv \max\{0, v_k - d_k\}, \quad k = 1, \ldots, n_R, \quad (3b)
\]

- \( v_k \): the “projected demand” for the disaster relief item at point \( k \).
The Expected Values of Shortages and Surpluses

\[
E(\Delta_k^-) = \int_{v_k}^{\infty} (t - v_k) F_k(t) dt, \quad k = 1, \ldots, n_R, \quad (4a)
\]

\[
E(\Delta_k^+) = \int_{0}^{v_k} (v_k - t) F_k(t) dt, \quad k = 1, \ldots, n_R. \quad (4b)
\]
The Expected Values of Shortages and Surpluses

\[ E(\Delta_k^-) = \int_{v_k}^{\infty} (t - v_k)F_k(t)dt, \quad k = 1, \ldots, n_R, \quad (4a) \]

\[ E(\Delta_k^+) = \int_{0}^{v_k} (v_k - t)F_k(t)dt, \quad k = 1, \ldots, n_R. \quad (4b) \]

The Expected Penalties due to Shortages and Surpluses

\[ E(\lambda_k^- \Delta_k^- + \lambda_k^+ \Delta_k^+) = \lambda_k^- E(\Delta_k^-) + \lambda_k^+ E(\Delta_k^+), \quad k = 1, \ldots, n_R, \quad (5) \]

\( \lambda_k^- \): the unit penalty associated with the shortage of the relief item at point \( k \),

\( \lambda_k^+ \): the unit penalty associated with the surplus of the relief item at point \( k \).
Path Flows

\[ x_p \geq 0, \quad \forall p \in \mathcal{P}. \quad (6) \]

\( x_p \): the flow of the disaster relief goods on path \( p \) joining node 1 with a demand node.
Path Flows

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Relationship between Path Flows and Projected Demand

\[ v_k \equiv \sum_{p \in \mathcal{P}_k} x_p, \quad k = 1, \ldots, n_R. \]  \hspace{1cm} (7)
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Relationship between Link Flows and Path Flows

\[ f_a = \sum_{p \in \mathcal{P}} x_p \delta_{ap}, \quad \forall a \in L. \]  \hspace{1cm} (8)
Completion Time on Links

\[ \tau_a(f_a) = g_a f_a + h_a, \quad \forall a \in L, \quad (9) \]

where:
\( \tau_a \): the completion time of the activity on link \( a \). Note: \( h_a \geq 0 \), and \( g_a \geq 0 \).
**Completion Time on Paths**

\[
\tau_p = \sum_{a \in L} \tau_a(f_a)\delta_{ap} = \sum_{a \in L} (g_a f_a + h_a)\delta_{ap}, \quad \forall p \in P. \tag{10}
\]

\(\tau_p\): the completion time of the sequence of activities on path \(p\).

\[
h_p = \sum_{a \in L} h_a\delta_{ap}, \quad \forall p \in P. \tag{11}
\]

Hence,

\[
\tau_p = h_p + \sum_{a \in L} g_a f_a \delta_{ap}, \quad \forall p \in P. \tag{12}
\]

\(h_p\): the sum of the uncongested terms \(h_a\)s on path \(p\).
Time Targets

\[ \tau_p \leq T_k, \quad \forall p \in P_k; \quad k = 1, \ldots, n_R, \quad (13) \]

\( T_k \): the target for the completion time of the activities on paths corresponding to demand point \( k \) determined by the organization.

\[ \sum_{a \in L} g_af_a\delta_{ap} \leq T_k - h_p, \quad \forall p \in P_k; \quad k = 1, \ldots, n_R. \quad (14) \]

\[ T_{kp} = T_k - h_p, \quad \forall p \in P_k; \quad k = 1, \ldots, n_R. \quad (15) \]

\( T_{kp} \): the target time for demand point \( k \) with respect to path \( p \).

\[ \sum_{a \in L} g_af_a\delta_{ap} \leq T_{kp}, \quad \forall p \in P_k; \quad k = 1, \ldots, n_R. \quad (16) \]
Capturing Time

Late Delivery with Respect to Target Times

\[ \sum_{a \in L} g_a f_a \delta_{ap} - z_p \leq T_{kp}, \quad \forall p \in P_k; \quad k = 1, \ldots, n_R. \quad (17) \]

\( z_p \): the amount of deviation with respect to target time \( T_{kp} \) corresponding to the “late” delivery of product to point \( k \) on path \( p \).
**Capturing Time**

**Nonnegativity Assumption**

\[ z_p \geq 0, \quad \forall p \in P_k; \quad k = 1, \ldots, n_R. \] (18)
Nonnegativity Assumption

\[ z_p \geq 0, \quad \forall p \in \mathcal{P}_k; \quad k = 1, \ldots, n_R. \]  \hfill (18)

Time Constraints

\[ \sum_{q \in \mathcal{P}} \sum_{a \in \mathcal{L}} g_{aq} x_q \delta_{aq} \delta_{ap} - z_p \leq T_{kp}, \quad \forall p \in \mathcal{P}_k; \quad k = 1, \ldots, n_R. \]  \hfill (19)
Capturing Time

Nonnegativity Assumption

\[ z_p \geq 0, \quad \forall p \in \mathcal{P}_k; \quad k = 1, \ldots, n_R. \]  \hspace{1cm} (18)

Time Constraints

\[ \sum_{q \in \mathcal{P}} \sum_{a \in \mathcal{L}} g_{aq} \delta_{aq} \delta_{ap} - z_p \leq T_{kp}, \quad \forall p \in \mathcal{P}_k; \quad k = 1, \ldots, n_R. \]  \hspace{1cm} (19)

\[ \hat{C}_p(x) = x_p \times C_p(x) = x_p \times \sum_{a \in \mathcal{L}} c_a(f_a)\delta_{ap}, \quad \forall p \in \mathcal{P}, \]  \hspace{1cm} (20)

\( \hat{C}_p(x) \): the total operational cost function on path \( p \).

\( C_p \): the unit operational cost on path \( p \).
The Optimization Formulation

Minimize \( \sum_{p \in \mathcal{P}} \hat{C}_p(x) + \sum_{k=1}^{n_R} (\lambda_k^- E(\Delta_k^-) + \lambda_k^+ E(\Delta_k^+)) + \sum_{k=1}^{n_R} \gamma_k(z), \)

subject to: constraints (6), (18), and (19), where \( \gamma_k(z) \) is the tardiness penalty function corresponding to demand point \( k \).
The Optimization Formulation

Minimize \[ \sum_{p \in P} \hat{C}_p(x) + \sum_{k=1}^{n_R} (\lambda_k^- E(\Delta_k^-) + \lambda_k^+ E(\Delta_k^+)) + \sum_{k=1}^{n_R} \gamma_k(z), \] \( (21) \)

subject to: constraints (6), (18), and (19), where \( \gamma_k(z) \) is the tardiness penalty function corresponding to demand point \( k \).

The Feasible Set

\[ K = \{(x, z, \omega) | x \in R^{np}_+, z \in R^{np}_+, \text{ and } \omega \in R^{np}_+ \}, \] \( (22) \)

where \( x \) is the vector of path flows, \( z \) is the vector of time deviations on paths, and \( \omega \) is the vector of Lagrange multipliers corresponding to (19).
Theorem: The Variational Inequality Formulation

The optimization problem (21), subject to its constraints (6), (18), and (19), is equivalent to the variational inequality problem: determine the vectors of optimal path flows, optimal path time deviations, and optimal Lagrange multipliers \((x^*, z^*, \omega^*) \in K\), such that:

\[
\begin{align*}
\sum_{k=1}^{n_R} \sum_{p \in P_k} \left[ \frac{\partial \hat{C}_p(x^*)}{\partial x_p} + \lambda^+_k P_k \left( \sum_{q \in P_k} x^*_q \right) - \lambda^-_k (1 - P_k \left( \sum_{q \in P_k} x^*_q \right)) \right] \\
+ \sum_{q \in P} \sum_{a \in L} \omega^*_q g_a \delta_{aq} \delta_{ap} \times [x_p - x^*_p] + \sum_{k=1}^{n_R} \sum_{p \in P_k} \left[ \frac{\partial \gamma_k(z^*)}{\partial z_p} - \omega^*_p \right] \times [z_p - z^*_p] \\
+ \sum_{k=1}^{n_R} \sum_{p \in P_k} \left[ T_{kp} + z^*_p - \sum_{q \in P} \sum_{a \in L} g_a x^*_q \delta_{aq} \delta_{ap} \right] \times [\omega_p - \omega^*_p] & \geq 0, \ \forall (x, z, \omega) \in K, \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ (23)
\end{align*}
\]

where

\[
\frac{\partial \hat{C}_p(x)}{\partial x_p} \equiv \sum_{a \in L} \frac{\partial \hat{c}_a(f_a)}{\partial f_a} \delta_{ap}, \quad \forall p \in P_k; \ k = 1, \ldots, n_R. \ \ \ \ \ \ \ (24)
\]
Consider the simple disaster relief supply chain network topology in Figure 2. There are 2 modes of transportation with links \( d \) and \( e \) representing ground and air transportation, respectively.

**Figure:** Supply Chain Network Topology for an Illustrative Numerical Example
An Illustrative Example

The total operational cost functions on the links are:

\[ \hat{c}_a(f_a) = 3f_a^2 + 2f_a, \quad \hat{c}_b(f_b) = f_b^2 + 3f_b, \quad \hat{c}_c(f_c) = 2f_c^2 + f_c, \]
\[ \hat{c}_d(f_d) = 4f_d^2 + 3f_d, \quad \hat{c}_e(f_e) = 7f_e^2 + 5f_e, \]
\[ \hat{c}_f(f_f) = f_f^2 + 4f_f, \quad \hat{c}_g(f_g) = 3f_g^2 + 2f_g. \]

There are two paths: \( p_1 \equiv (a, b, c, d, f, g), \) \( p_2 \equiv (a, b, c, e, f, g). \)
An Illustrative Example

The demand for the relief item at the demand point follows a uniform distribution on the interval \([5,10]\); therefore, the probability distribution function of demand at the demand point is:

\[
P_{R_1}(v_{R_1}) = \frac{v_{R_1} - 5}{10 - 5} = \frac{x_{p_1} + x_{p_2} - 5}{5}.
\]

The unit shortage and surplus penalties are: \(\lambda^{-}_{R_1} = 5000\) and \(\lambda^{+}_{R_1} = 100\).
The organization is interested in the pre-positioning strategy; i.e., it wishes to determine the amount of the relief item that should be stored beforehand. Hence, the completion time on links $a$, $b$, and $c$ (procurement, transportation, and storage) is set to zero:

$$\tau_a(f_a) = \tau_b(f_b) = \tau_c(f_c) = 0.$$  

The completion time functions on the rest of the links are:

$$\tau_d(f_d) = 9f_d + 6, \quad \tau_e(f_e) = 2f_e + 2,$$

$$\tau_f(f_f) = 1.5f_f + 2, \quad \tau_g(f_g) = 5f_g + 4.$$  

The target time at demand point $R_1$ is 72 hours:

$$T_{R_1} = 72, \quad \forall p \in \mathcal{P}_{R_1}.$$
The decision-maker assigns a higher tardiness penalty to $p_2$ in that the expectation of on-time delivery from the path with the air transportation link was higher, so the tardiness penalty function at the demand point was:

$$\gamma_{R_1}(z) = 3.5z^2_{p_1} + 8z^2_{p_2}.$$
The solution to this problem can be obtained by solving a system of equations as we demonstrate in our paper.

The optimal path flows are:

\[ x_{p_1}^* = 1.04 \text{ and } x_{p_2}^* = 7.50 \]

and the optimal values of link flows:

\[ f_a^* = f_b^* = f_c^* = f_f^* = f_g^* = 8.54, \quad f_d^* = 1.04, \quad f_e^* = 7.50. \]

The value of the projected demand at \( R_1 \) is:

\[ v_{R_1}^* = x_{p_1}^* + x_{p_2}^* = 8.54, \]

which is the amount that needs to be pre-positioned at the storage facility.
The optimal time deviations on paths $p_1$ and $p_2$ with respect to the target of 72 hours are:

$$z_{p_1}^* = 4.85 \text{ and } z_{p_2}^* = 6.47.$$  

Neither of the two transportation modes to the affected area would be able to satisfy the target time requirement. Interestingly, the time deviation is higher on the path that contains the air route, which is due to the majority of the load being allocated to this mode.

The optimal values of the Lagrange multipliers corresponding to the time goal constraints are:

$$\omega_{p_1}^* = 33.97 \text{ and } \omega_{p_2}^* = 103.55.$$
This example addresses the post-disaster procurement strategy – as opposed to pre-positioning of the supplies. We assumed that the organization did not store disaster items beforehand. In other words, the organization would procure relief items only once a disaster struck.

Figure: Supply Chain Network Topology for a Variant of the Illustrative Numerical Example
A Variant of the Illustrative Example

The total cost functions and the time completion functions on links $d, e, f,$ and $g$ remain the same as in the illustrative example. As for link $h$, we have:

$$\hat{c}_h(f_h) = 5f_h^2 + 3f_h \quad \text{and} \quad \tau_h(f_h) = 3f_h + 3.$$ 

In this example, the total operational cost on the post-disaster procurement link, $h$, is higher than that on the pre-disaster procurement link $a$ in the original example. The set of paths in this problem is $P = \{p_3, p_4\}$ where $p_3 \equiv (h, d, f, g)$ and $p_4 \equiv (h, e, f, g)$.

The demand distribution, the shortage and surplus penalties, as well as the target time are identical to those in the previous problem.
The tardiness penalty function at the demand point is the same, except that now it is a function of the time deviations on new paths:

\[ \gamma_{R_1}(z) = 3.5z_{p_3}^2 + 8z_{p_4}^2. \]
Solution of the Variant

This example can also be solved using a system of equations as in the paper. The optimal path flows are:

\[ x_{p_3}^* = 0.33, \quad x_{p_4}^* = 6.26, \]

which yields the following optimal link flows:

\[ f_h^* = f_f^* = f_g^* = 6.59, \quad f_d^* = 0.33, \quad f_e^* = 6.26. \]

Note that, under a post-disaster procurement strategy, the optimal flow on the ground transportation link is significantly lower than that in the pre-disaster procurement strategy. In addition, the optimal flow on the air transportation link has experienced a 17% decrease which is a consequence of increased operational costs.
Solution of the Variant

The value of the projected demand is:

\[ v_{R_1}^* = x_{p_3}^* + x_{p_4}^* = 6.59, \]

which is 23% lower than that for the original example.

The optimal time deviations on paths \( p_3 \) and \( p_4 \) are:

\[ z_{p_3}^* = 8.54, \quad z_{p_4}^* = 14.09, \]

which are higher than their respective values in the first example. The incurred tardiness penalty value, \( \gamma_{R_1}(z^*) \), is equal to 1,844.16, i.e., a 321% increase from that in the first example.

The optimal Lagrange multipliers on paths \( p_3 \) and \( p_4 \) are:

\[ \omega_{p_3}^* = 59.77, \quad \omega_{p_4}^* = 225.49. \]
Table 1 displays the optimal values of the path flows, $x_{p3}^*$ and $x_{p4}^*$, the path time deviations, $z_{p3}^*$ and $z_{p4}^*$, and the Lagrange multipliers, $\omega_{p3}^*$ and $\omega_{p4}^*$, as the unit shortage penalty, $\lambda_{\bar{R}_1}$, is increased from 2,500 to 12,500 in the variant.

Table: Sensitivity Analysis of the Optimal Solution to the Unit Shortage Penalty at the Demand Point for the Variant Example

<table>
<thead>
<tr>
<th>$\lambda_{\bar{R}_1}$</th>
<th>$x_{p3}^*$</th>
<th>$x_{p4}^*$</th>
<th>$z_{p3}^*$</th>
<th>$z_{p4}^*$</th>
<th>$\omega_{p3}^*$</th>
<th>$\omega_{p4}^*$</th>
<th>Value of OF (21)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2,500</td>
<td>0.50</td>
<td>5.56</td>
<td>5.09</td>
<td>7.66</td>
<td>35.66</td>
<td>122.58</td>
<td>5,081.96</td>
</tr>
<tr>
<td>5,000</td>
<td>0.33</td>
<td>6.26</td>
<td>8.54</td>
<td>14.09</td>
<td>59.77</td>
<td>225.49</td>
<td>8,440.02</td>
</tr>
<tr>
<td>7,500</td>
<td>0.20</td>
<td>6.79</td>
<td>11.18</td>
<td>19.02</td>
<td>78.25</td>
<td>304.39</td>
<td>11,021.81</td>
</tr>
<tr>
<td>10,000</td>
<td>0.09</td>
<td>7.22</td>
<td>13.26</td>
<td>22.91</td>
<td>92.80</td>
<td>366.49</td>
<td>13,035.31</td>
</tr>
<tr>
<td>12,500</td>
<td>0.01</td>
<td>7.56</td>
<td>14.94</td>
<td>26.05</td>
<td>104.57</td>
<td>416.72</td>
<td>14,655.25</td>
</tr>
</tbody>
</table>
As seen in Table 1, as the shortage penalty increases, the organization will be fulfilling a higher projected demand, $x_{p_3}^* + x_{p_4}^*$, by assigning higher quantities to the path that uses air transportation to the affected region.

At $\lambda^{-}_{R_1} = 12,500$, the optimal path flow on the ground transportation path is almost zero, which means that the organization relies on the air transport mode. Handling larger volumes of goods increases the congestion on paths which, in turn, worsens the lateness of deliveries to the region.
The Algorithm

Explicit Formulae for the Euler Method (Dupuis and Nagurney (1993)) Applied to Variational Inequality (23)

At iteration $\tau + 1$, compute the path flows, the path time deviations, and the Lagrange multipliers, according to:

$$x_p^{\tau+1} = \max\{0, x_p^\tau + a_\tau (\lambda_k^- (1 - P_k (\sum_{q \in P_k} x_q^\tau)) - \lambda_k^+ P_k (\sum_{q \in P_k} x_q^\tau)) - \frac{\partial \hat{C}_p(x^\tau)}{\partial x_p}$$

$$- \sum_{q \in P} \sum_{a \in L} \omega_q^\tau g_a \delta_{aq} \delta_{ap}\}, \quad \forall p \in P_k, \forall k,$$  \hspace{1cm} (25)

$$z_p^{\tau+1} = \max\{0, z_p^\tau + a_\tau (\omega_p^\tau - \frac{\partial \gamma_k(z^\tau)}{\partial z_p})\}, \quad \forall p \in P_k, \forall k,$$  \hspace{1cm} (26)

$$\omega_p^{\tau+1} = \max\{0, \omega_p^\tau + a_\tau (\sum_{q \in P} \sum_{a \in L} g_a x_q^\tau \delta_{aq} \delta_{ap} - T_{kp} - z_p^\tau\}, \quad \forall p \in P_k, \forall k.$$  \hspace{1cm} (27)
Background for the Larger Numerical Examples

The scenario for the first larger numerical example is built on the possibility of another earthquake striking Haiti. We then construct a variant.

The next figure displays the disaster relief supply chain network topology corresponding to the case of a Haiti earthquake.

Node 1 represents the American Red Cross. We assume that the Red Cross can utilize two of its disaster aid zones in the US, one in Maryland, representing the Northeast and the East, and the other one in Florida, the closest state to the Caribbean. Each of the two zones is assumed to possess a single procurement facility, a single storage facility, and a single departure portal.
The Supply Chain Network Topology

Figure: Network Topology of the Disaster Relief Supply Chain Numerical Examples
Both locations have the ability to start procuring the relief goods after an earthquake strikes when and if the need arises (links 3 and 4). These procured/purchased goods at the zones are directly sent to their respective departure portals bypassing the storage phase. Next, from these departure facilities, the collected items whether pre-positioned beforehand or just procured are sent via air or sea to the affected region.

We assume that the facility $S_{1,2}$, Maryland, would cover the arrival facility $A_1$ in Haiti, and the facility $S_{2,2}$ would serve the arrival port $A_2$ in the Dominican Republic.

Links 9 and 12 represent air transportation whereas links 10 and 11 correspond to marine transportation. After the arrived cargo is sorted and processed, relief items are distributed to the points of demand, $R_1$ and $R_2$, both located in Haiti.
Links 15 and 20 correspond to the distribution of goods by helicopter, whereas links 16 through 19 represent ground distribution.

We allow for each of the two processing facilities located in Haiti and the Dominican Republic, i.e., $B_1$ and $B_2$, to ship to both of the two demand points in Haiti.
The Euler method (cf. (25)–(27)) for the solution of variational inequality (23) was implemented in FORTRAN on a Linux system at the University of Massachusetts Amherst. We set the sequence as \( \{a^\tau\} = .1(1, \frac{1}{2}, \frac{1}{2}, \ldots) \), and the convergence tolerance was \( 10^{-6} \).

The unit shortage and surplus penalties at demand points \( R_1 \) and \( R_2 \):

\[
\lambda^-_{R_1} = 10,000, \quad \lambda^+_{R_1} = 100, \\
\lambda^-_{R_2} = 7,500, \quad \lambda^+_{R_2} = 150.
\]

The target times of delivery at demand points:

\[
T_{R_1} = 72, \quad T_{R_2} = 70.
\]

The tardiness penalty functions at demand points:

\[
\gamma_{R_1}(z) = 3\left( \sum_{p \in \mathcal{P}_{R_1}} z_{p}^2 \right), \quad \gamma_{R_2}(z) = 3\left( \sum_{p \in \mathcal{P}_{R_2}} z_{p}^2 \right).
\]
Table 2: Link Total Cost and Time Functions and Optimal Link Flows

<table>
<thead>
<tr>
<th>Link</th>
<th>( \hat{c}_a(f_a) )</th>
<th>( \tau_a(f_a) )</th>
<th>( f^*_a )</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>( 3f_1^2 + 2f_1 )</td>
<td>0</td>
<td>19.22</td>
</tr>
<tr>
<td>2</td>
<td>( 2f_2^2 + 2.5f_2 )</td>
<td>0</td>
<td>20.02</td>
</tr>
<tr>
<td>3</td>
<td>( 5f_3^2 + 4f_3 )</td>
<td>( 3f_3 + 3 )</td>
<td>0.00</td>
</tr>
<tr>
<td>4</td>
<td>( 4.5f_4^2 + 3f_4 )</td>
<td>( 4f_4 + 2 )</td>
<td>0.00</td>
</tr>
<tr>
<td>5</td>
<td>( f_5^2 + 2f_5 )</td>
<td>0</td>
<td>19.22</td>
</tr>
<tr>
<td>6</td>
<td>( f_6^2 + .5f_6 )</td>
<td>0</td>
<td>20.02</td>
</tr>
<tr>
<td>7</td>
<td>( 2.5f_7^2 + 3f_7 )</td>
<td>0</td>
<td>19.22</td>
</tr>
<tr>
<td>8</td>
<td>( 3.5f_8^2 + 2f_8 )</td>
<td>0</td>
<td>20.02</td>
</tr>
<tr>
<td>9</td>
<td>( 7f_9^2 + 5f_9 )</td>
<td>( 2f_9 + 2 )</td>
<td>19.22</td>
</tr>
<tr>
<td>10</td>
<td>( 4f_{10}^2 + 6f_{10} )</td>
<td>( 10f_{10} + 6 )</td>
<td>0.00</td>
</tr>
<tr>
<td>11</td>
<td>( 2.5f_{11}^2 + 4f_{11} )</td>
<td>( 7.5f_{11} + 5 )</td>
<td>0.23</td>
</tr>
<tr>
<td>12</td>
<td>( 4.5f_{12}^2 + 5f_{12} )</td>
<td>( 1.5f_{12} + 1.5 )</td>
<td>19.79</td>
</tr>
<tr>
<td>13</td>
<td>( 2f_{13}^2 + 4f_{13} )</td>
<td>( 2f_{13} + 2 )</td>
<td>19.22</td>
</tr>
<tr>
<td>14</td>
<td>( f_{14}^2 + 3f_{14} )</td>
<td>( 1.5f_{14} + 1 )</td>
<td>20.02</td>
</tr>
<tr>
<td>15</td>
<td>( 4f_{15}^2 + 5f_{15} )</td>
<td>( 3f_{15} + 3 )</td>
<td>13.95</td>
</tr>
<tr>
<td>16</td>
<td>( 2.5f_{16}^2 + 2f_{16} )</td>
<td>( 5f_{16} + 4 )</td>
<td>5.28</td>
</tr>
<tr>
<td>17</td>
<td>( 3f_{17}^2 + 4f_{17} )</td>
<td>( 6.5f_{17} + 3 )</td>
<td>0.00</td>
</tr>
<tr>
<td>18</td>
<td>( 4f_{18}^2 + 4f_{18} )</td>
<td>( 7f_{18} + 5 )</td>
<td>6.85</td>
</tr>
<tr>
<td>19</td>
<td>( 3f_{19}^2 + 3f_{19} )</td>
<td>( 4f_{19} + 5 )</td>
<td>5.68</td>
</tr>
<tr>
<td>20</td>
<td>( 3.5f_{20}^2 + 5f_{20} )</td>
<td>( 3.5f_{20} + 4 )</td>
<td>7.49</td>
</tr>
</tbody>
</table>
As seen in Table 2, the optimal flows on links 3 and 4, i.e., the post-disaster procurement links, are zero. Hence, given the demand information and the cost and time functions on the supply chain network links, the organization would be better off by adopting the pre-positioning strategy.

In addition, links 10 and 11, corresponding to marine transportation of goods from the US to the affected region have zero or very small flows. Such an outcome is due to the importance of timely deliveries, and, thus, the organization needs to ship via air to minimize the lateness on the demand end.
Similarly, among the distribution links, the ones representing shipments by helicopter (links 15 and 20) are assigned relatively higher loads whereas link 17 corresponding to one of the ground distribution links will not be utilized.

Also, the optimal flows are almost equal on links 1 and 2 suggests an even split of pre-positioning of the load between the two US aid regions.
Table 3: Path Definitions, Target Times, **Optimal Path Flows**, Time Deviations, and Lagrange Multipliers

<table>
<thead>
<tr>
<th>Path Definition</th>
<th>$T_{kp}$</th>
<th>$x_p^*$</th>
<th>$z_p^*$</th>
<th>$\omega_p^*$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$p_1 = (1, 5, 7, 9, 13, 15)$</td>
<td>65</td>
<td>13.95</td>
<td>53.66</td>
<td>321.99</td>
</tr>
<tr>
<td>$p_2 = (1, 5, 7, 9, 13, 16)$</td>
<td>64</td>
<td>5.28</td>
<td>39.23</td>
<td>235.39</td>
</tr>
<tr>
<td>$p_3 = (1, 5, 7, 10, 13, 15)$</td>
<td>61</td>
<td>0.00</td>
<td>19.32</td>
<td>115.90</td>
</tr>
<tr>
<td>$p_4 = (1, 5, 7, 10, 13, 16)$</td>
<td>60</td>
<td>0.00</td>
<td>4.83</td>
<td>28.99</td>
</tr>
<tr>
<td>$p_5 = (2, 6, 8, 11, 14, 18)$</td>
<td>61</td>
<td>0.06</td>
<td>18.67</td>
<td>112.03</td>
</tr>
<tr>
<td>$p_6 = (2, 6, 8, 12, 14, 18)$</td>
<td>64.5</td>
<td>6.79</td>
<td>43.12</td>
<td>258.75</td>
</tr>
<tr>
<td>$p_7 = (3, 9, 13, 15)$</td>
<td>62</td>
<td>0.00</td>
<td>56.66</td>
<td>339.99</td>
</tr>
<tr>
<td>$p_8 = (3, 9, 13, 16)$</td>
<td>61</td>
<td>0.00</td>
<td>42.23</td>
<td>253.39</td>
</tr>
<tr>
<td>$p_9 = (3, 10, 13, 15)$</td>
<td>58</td>
<td>0.00</td>
<td>22.34</td>
<td>134.05</td>
</tr>
<tr>
<td>$p_{10} = (3, 10, 13, 16)$</td>
<td>57</td>
<td>0.00</td>
<td>7.84</td>
<td>47.03</td>
</tr>
<tr>
<td>$p_{11} = (4, 11, 14, 18)$</td>
<td>59</td>
<td>0.00</td>
<td>20.71</td>
<td>124.24</td>
</tr>
<tr>
<td>$p_{12} = (4, 12, 14, 18)$</td>
<td>62.5</td>
<td>0.00</td>
<td>45.24</td>
<td>271.46</td>
</tr>
</tbody>
</table>

**$\mathcal{P}_{R_1}$: Set of Paths Corresponding to Demand Point $R_1$**

<table>
<thead>
<tr>
<th>Path Definition</th>
<th>$T_{kp}$</th>
<th>$x_p^*$</th>
<th>$z_p^*$</th>
<th>$\omega_p^*$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$p_{13} = (1, 5, 7, 9, 13, 17)$</td>
<td>63</td>
<td>0.00</td>
<td>13.87</td>
<td>83.25</td>
</tr>
<tr>
<td>$p_{14} = (1, 5, 7, 10, 13, 17)$</td>
<td>59</td>
<td>0.00</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>$p_{15} = (2, 6, 8, 11, 14, 19)$</td>
<td>59</td>
<td>0.13</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>$p_{16} = (2, 6, 8, 11, 14, 20)$</td>
<td>60</td>
<td>0.04</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>$p_{17} = (2, 6, 8, 12, 14, 19)$</td>
<td>62.5</td>
<td>5.55</td>
<td>19.91</td>
<td>119.44</td>
</tr>
<tr>
<td>$p_{18} = (2, 6, 8, 12, 14, 20)$</td>
<td>63.5</td>
<td>7.45</td>
<td>22.40</td>
<td>134.43</td>
</tr>
<tr>
<td>$p_{19} = (3, 9, 13, 17)$</td>
<td>60</td>
<td>0.00</td>
<td>16.90</td>
<td>101.41</td>
</tr>
<tr>
<td>$p_{20} = (3, 10, 13, 17)$</td>
<td>56</td>
<td>0.00</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>$p_{21} = (4, 11, 14, 19)$</td>
<td>57</td>
<td>0.00</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>$p_{22} = (4, 11, 14, 20)$</td>
<td>58</td>
<td>0.00</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>$p_{23} = (4, 12, 14, 19)$</td>
<td>60.5</td>
<td>0.00</td>
<td>21.96</td>
<td>131.77</td>
</tr>
<tr>
<td>$p_{24} = (4, 12, 14, 20)$</td>
<td>61.5</td>
<td>0.00</td>
<td>24.48</td>
<td>146.85</td>
</tr>
</tbody>
</table>

**$\mathcal{P}_{R_2}$: Set of Paths Corresponding to Demand Point $R_2$**
From Table 3 we see that, among the 24 paths in the supply chain network, fewer than one-third have considerable positive flows since the others involve links that are either costlier or more time-consuming.

From the optimal values of time deviations on paths, one can observe that significant deviations from the target times have occurred on several paths in the network. This seems to be more of an issue in the paths connecting the origin to demand point $R_1$, i.e., the hypothetically more vulnerable location.

**Such an outcome may mandate additional investments on critical transportation/distribution channels to $R_1$ which can be done in accordance with the optimal values of respective Lagrange multipliers.**
The higher the value of the Lagrange multiplier on a path, the more improvement in time can be attained by enhancing that path which, in turn, leads to a more efficient disaster response system.
We assumed that the organization will now procure the items \textit{locally} and, hence, the time functions associated with the direct procurement links 3 and 4 are now greatly reduced. The remainder of the input data remains the same as in the previous example.
# Table 4: Numerical Example Variant - Optimal Link Flows

<table>
<thead>
<tr>
<th>Link</th>
<th>$\hat{c}_a(f_a)$</th>
<th>$\tau_a(f_a)$</th>
<th>$f_a^*$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>$3f_1^2 + 2f_1$</td>
<td>0</td>
<td>12.02</td>
</tr>
<tr>
<td>2</td>
<td>$2f_2^2 + 2.5f_2$</td>
<td>0</td>
<td>11.21</td>
</tr>
<tr>
<td>3</td>
<td>$5f_3^2 + 4f_3$</td>
<td>$.1f_3 + 1$</td>
<td>7.35</td>
</tr>
<tr>
<td>4</td>
<td>$4.5f_4^2 + 3f_4$</td>
<td>$.1f_4 + 1$</td>
<td>8.88</td>
</tr>
<tr>
<td>5</td>
<td>$f_5^2 + 2f_5$</td>
<td>0</td>
<td>12.02</td>
</tr>
<tr>
<td>6</td>
<td>$f_6^2 + .5f_6$</td>
<td>0</td>
<td>11.21</td>
</tr>
<tr>
<td>7</td>
<td>$2.5f_7^2 + 3f_7$</td>
<td>0</td>
<td>12.02</td>
</tr>
<tr>
<td>8</td>
<td>$3.5f_8^2 + 2f_8$</td>
<td>0</td>
<td>11.21</td>
</tr>
<tr>
<td>9</td>
<td>$7f_9^2 + 5f_9$</td>
<td>$2f_9 + 2$</td>
<td>19.37</td>
</tr>
<tr>
<td>10</td>
<td>$4f_{10}^2 + 6f_{10}$</td>
<td>$10f_{10} + 6$</td>
<td>0.00</td>
</tr>
<tr>
<td>11</td>
<td>$2.5f_{11}^2 + 4f_{11}$</td>
<td>$7.5f_{11} + 5$</td>
<td>0.24</td>
</tr>
<tr>
<td>12</td>
<td>$4.5f_{12}^2 + 5f_{12}$</td>
<td>$1.5f_{12} + 1.5$</td>
<td>19.86</td>
</tr>
<tr>
<td>13</td>
<td>$2f_{13}^2 + 4f_{13}$</td>
<td>$2f_{13} + 2$</td>
<td>19.37</td>
</tr>
<tr>
<td>14</td>
<td>$f_{14}^2 + 3f_{14}$</td>
<td>$1.5f_{14} + 1$</td>
<td>20.10</td>
</tr>
<tr>
<td>15</td>
<td>$4f_{15}^2 + 5f_{15}$</td>
<td>$3f_{15} + 3$</td>
<td>14.04</td>
</tr>
<tr>
<td>16</td>
<td>$2.5f_{16}^2 + 2f_{16}$</td>
<td>$5f_{16} + 4$</td>
<td>5.33</td>
</tr>
<tr>
<td>17</td>
<td>$3f_{17}^2 + 4f_{17}$</td>
<td>$6.5f_{17} + 3$</td>
<td>0.00</td>
</tr>
<tr>
<td>18</td>
<td>$4f_{18}^2 + 4f_{18}$</td>
<td>$7f_{18} + 5$</td>
<td>6.84</td>
</tr>
<tr>
<td>19</td>
<td>$3f_{19}^2 + 3f_{19}$</td>
<td>$4f_{19} + 5$</td>
<td>5.72</td>
</tr>
<tr>
<td>20</td>
<td>$3.5f_{20}^2 + 5f_{20}$</td>
<td>$3.5f_{20} + 4$</td>
<td>7.53</td>
</tr>
</tbody>
</table>
As reported in Table 4, now both the storage links for pre-positioning (links 7 and 8) and for post-disaster procurement (links 3 and 4) have positive flows.

**Hence, with the new data (and decision to procure locally) the organization should engage in both strategies.**

The optimal solution suggests to the organization how much of the relief good should be stored and in which location and how much should also be procured (and from where) once the disaster strikes.
A network model was developed for the supply chain management of a disaster relief (humanitarian) organization in charge of procurement and distribution of relief items to a geographic region prone to natural disasters. The model:

- allows for the integration of two distinct policies by disaster relief organizations: (1) pre-positioning the supplies beforehand (2) procurement of necessary items once the disaster has occurred;
- includes penalties associated with shortages/surpluses at the demand points with respect to the uncertain demand, and
- enables prioritizing the demand points based on the population, geographic location, etc., by assigning different time targets.
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- allows for the integration of two distinct policies by disaster relief organizations: (1) pre-positioning the supplies beforehand (2) procurement of necessary items once the disaster has occurred;
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- allows for the integration of two distinct policies by disaster relief organizations: (1) pre-positioning the supplies beforehand (2) procurement of necessary items once the disaster has occurred;

- includes penalties associated with shortages/surpluses at the demand points with respect to the uncertain demand, and
Summary and Conclusions

A network model was developed for the supply chain management of a disaster relief (humanitarian) organization in charge of procurement and distribution of relief items to a geographic region prone to natural disasters. The model:

- allows for the integration of two distinct policies by disaster relief organizations: (1) pre-positioning the supplies beforehand (2) procurement of necessary items once the disaster has occurred;
- includes penalties associated with shortages/surpluses at the demand points with respect to the uncertain demand, and
- enables prioritizing the demand points based on the population, geographic location, etc., by assigning different time targets.